

Computing Moduli of Rings and Quadrilaterals with hp-FEM

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- Joint work with
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Flat-Earth Outline



The Known World

Flat-Earth Outline

FEM

Convex
Quadrilaterals

Capacity

Flat-Earth Outline

Ring Domains

FEM

Convex
Quadrilaterals

Capacity

Non-Convex
Quadrilaterals

Flat-Earth Outline

Ring Domains

FEM

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Quadrilaterals

Capacity

Non-Convex
Quadrilaterals

Here Be the 3D-Dragons

Objective:
**Compute the quantities
of interest as accurately
as possible using FEM.**

Dirichlet-Neumann Problem

Let D be a region in the complex plane whose boundary ∂D consists of a finite number of regular Jordan curves, so that at every point, except possibly at finitely many points, of the boundary a normal is defined. Let ψ to be a real-valued continuous function defined on ∂D . Let $\partial D = A \cup B$ where A, B both are unions of Jordan arcs. Find a function u satisfying the following conditions:

1. u is continuous and differentiable in \bar{D} .
2. $u(t) = \psi(t)$, for all $t \in A$.
3. If $\partial/\partial n$ denotes differentiation in the direction of the exterior normal, then

$$\frac{\partial}{\partial n} u(t) = \psi(t), \quad \text{for all } t \in B.$$

Modulus of a Quadrilateral

One can express the modulus of a quadrilateral $(D; z_1, z_2, z_3, z_4)$ in terms of the solution of the Dirichlet-Neumann problem as follows. Let $\gamma_j, j = 1, 2, 3, 4$ be the arcs of ∂D between (z_4, z_1) , (z_1, z_2) , (z_2, z_3) , (z_3, z_4) , respectively. If u is the (unique) harmonic solution of the Dirichlet-Neumann problem with boundary values of u equal to 0 on γ_2 , equal to 1 on γ_4 and with $\partial u / \partial n = 0$ on $\gamma_1 \cup \gamma_3$, then:

$$M(D; z_1, z_2, z_3, z_4) = \int_D |\nabla u|^2 dm.$$

Reciprocal identity: $M(D; z_1, z_2, z_3, z_4) \cdot M(D; z_2, z_3, z_4, z_1) = 1$

Modulus of a Polygon

Suppose that w is a vector of p complex numbers such that the points w_1, \dots, w_q , $q \geq 5$, are the vertices of a polygon D and that they define a positive orientation of the boundary. Choose indices $k_1, k_2 \in \{1, \dots, p-1\}$ with $k_1 < k_2$ and set $z_1 = w_{k_1}$, $z_2 = w_{k_1+1}$, $z_3 = w_{k_2}$, $z_4 = w_{k_2+1}$. Then we define

$$\text{cmodu}(w, k_1, k_2) = M(D; z_1, z_2, z_3, z_4),$$

$$\text{modu}(w, k_1, k_2) = M(D; z_2, z_3, z_4, z_1).$$

Reciprocal relation:

$$\text{cmodu}(w, k_1, k_2) \cdot \text{modu}(w, k_1, k_2) = 1.$$

Modulus of a Ring Domain

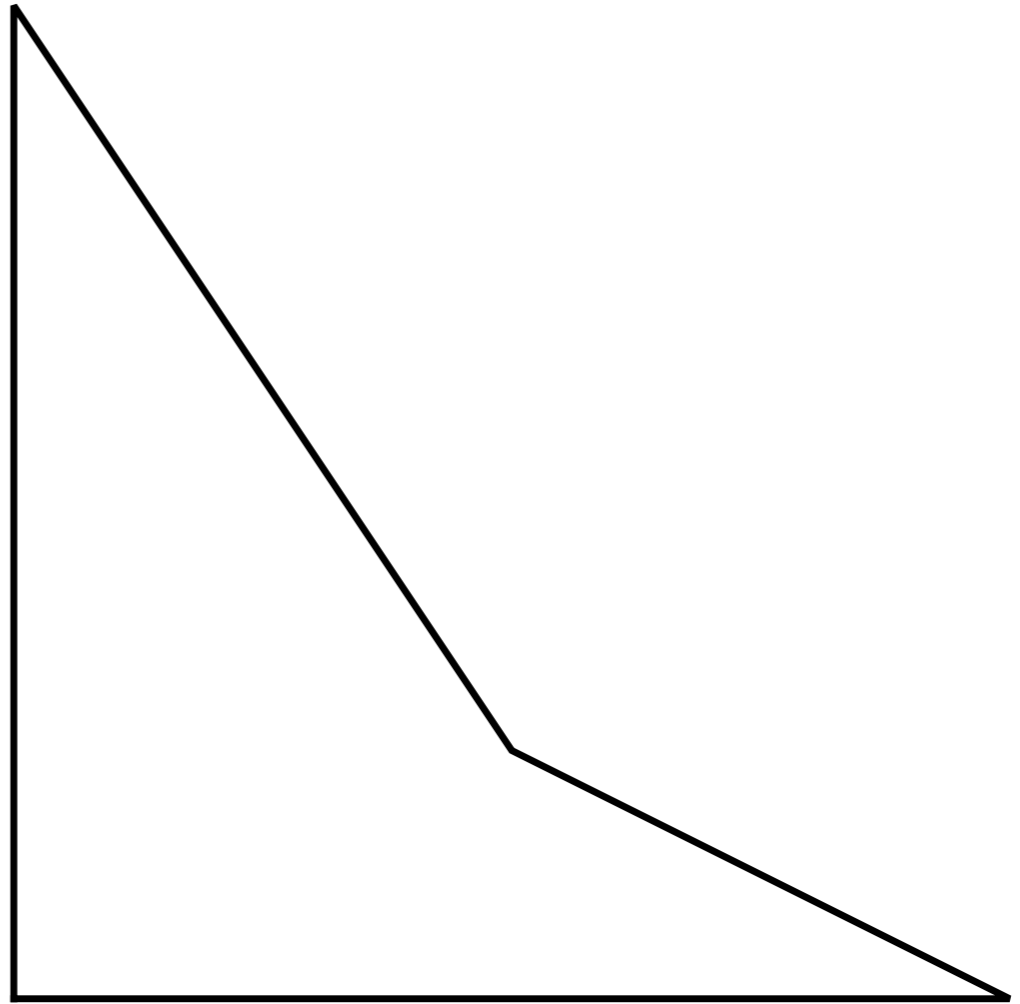
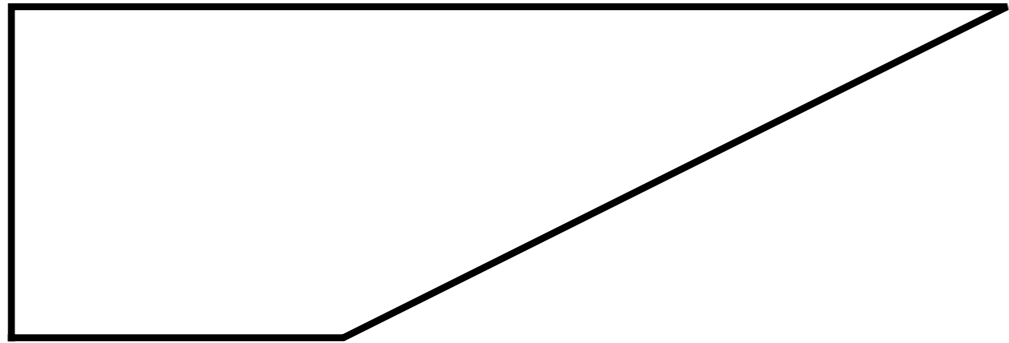
Let E and F be two disjoint compact sets in the extended complex plane. Then one of the sets E, F is bounded and without loss of generality we may assume that it is E . If both E and F are connected and the set $R = \mathbb{C} \setminus (E \cup F)$ is connected, then R is called a *ring domain*. In this case R is a doubly connected plane domain. The *capacity* of R is defined by

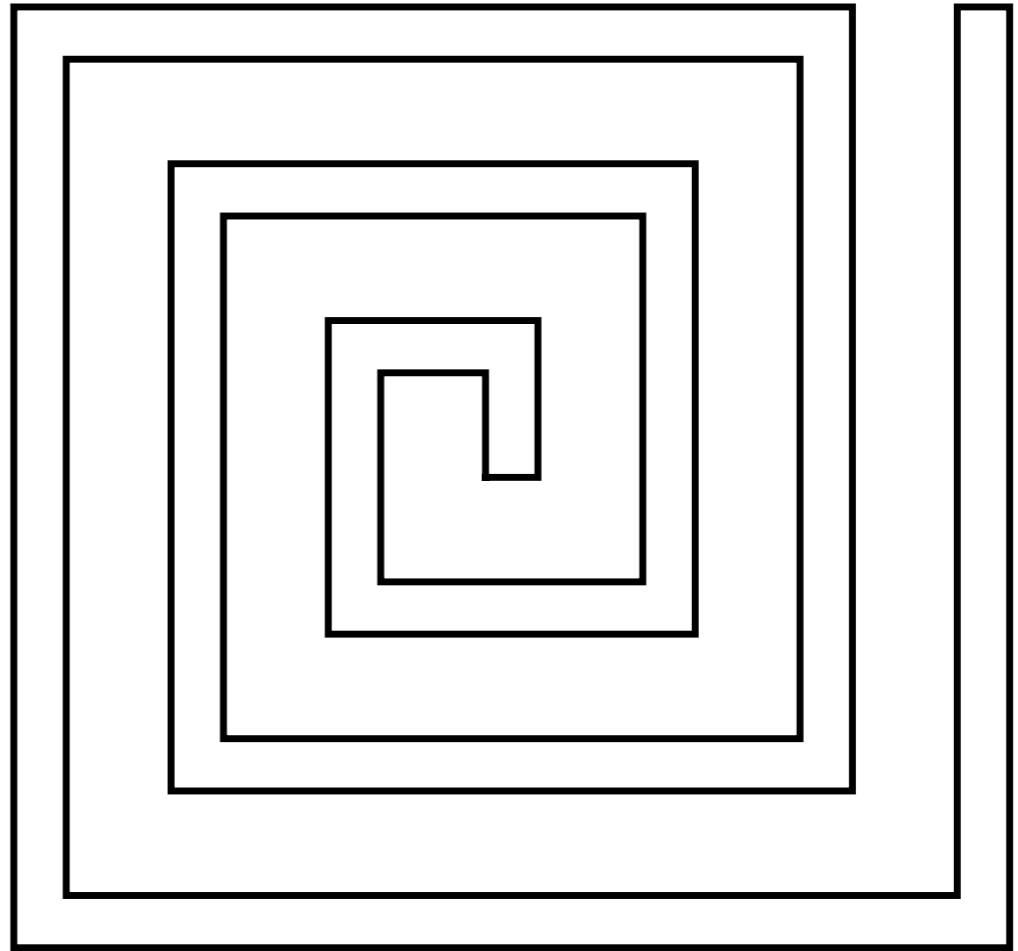
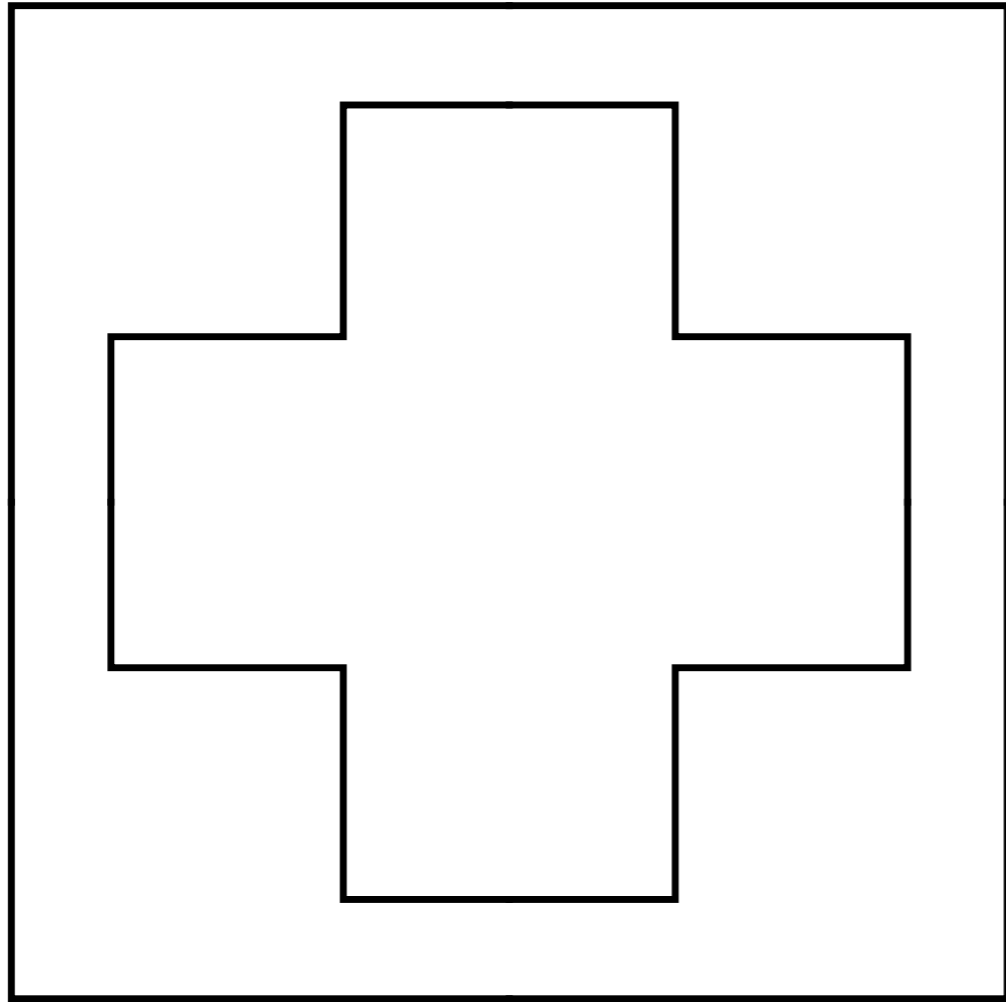
$$\text{cap } R = \inf_u \int_R |\nabla u|^2 dm,$$

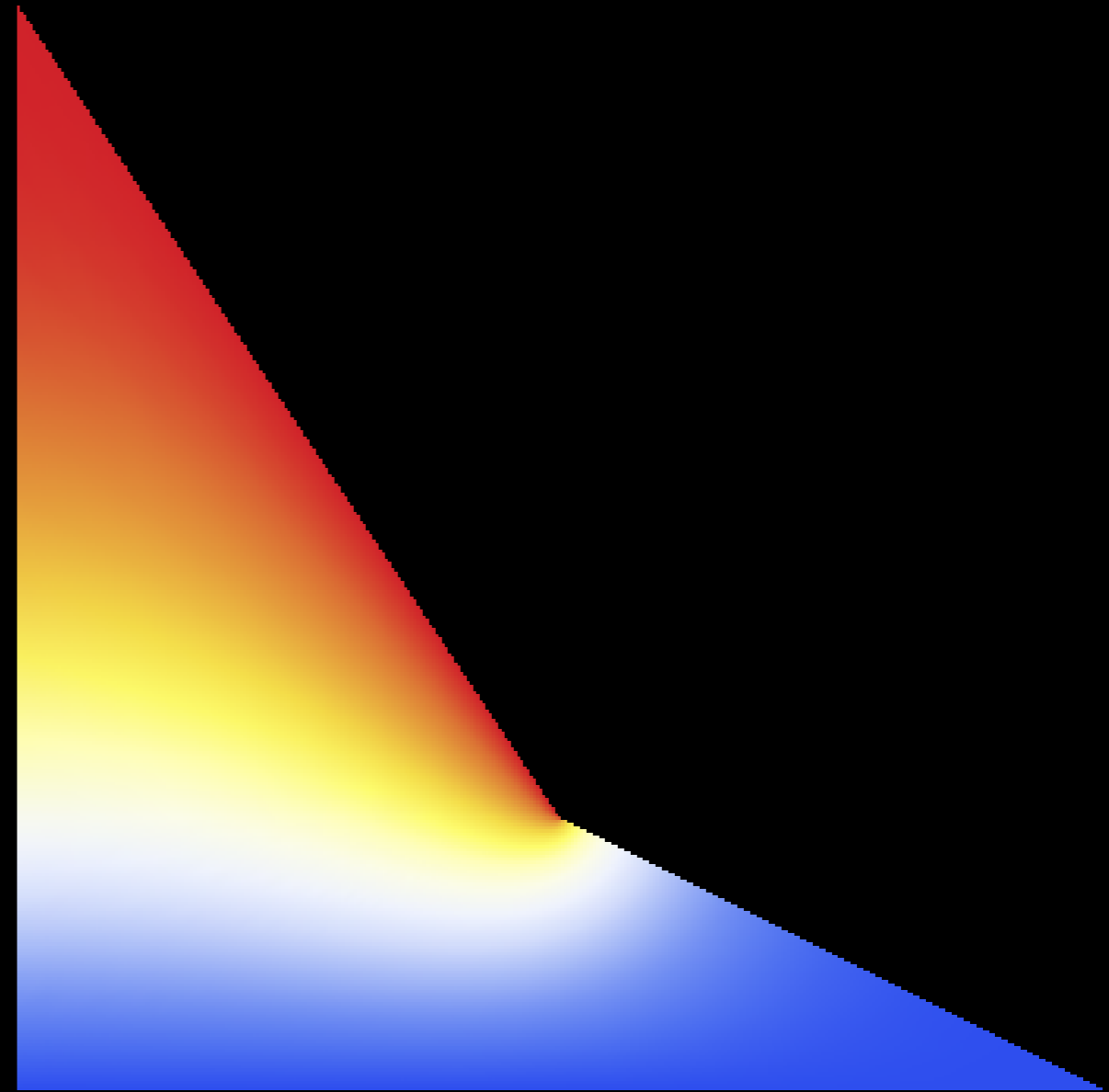
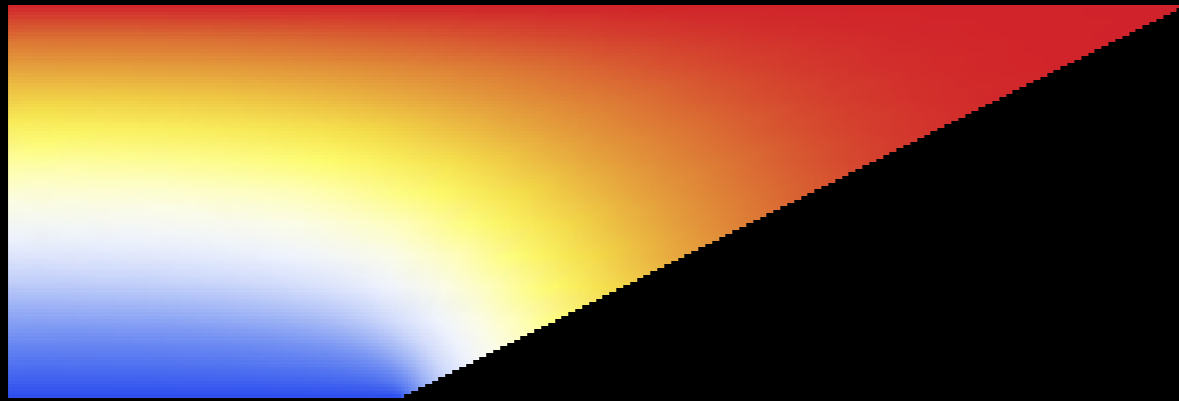
where the infimum is taken over all nonnegative, piecewise differentiable functions u with compact support in $R \cup E$ such that $u = 1$ on E .

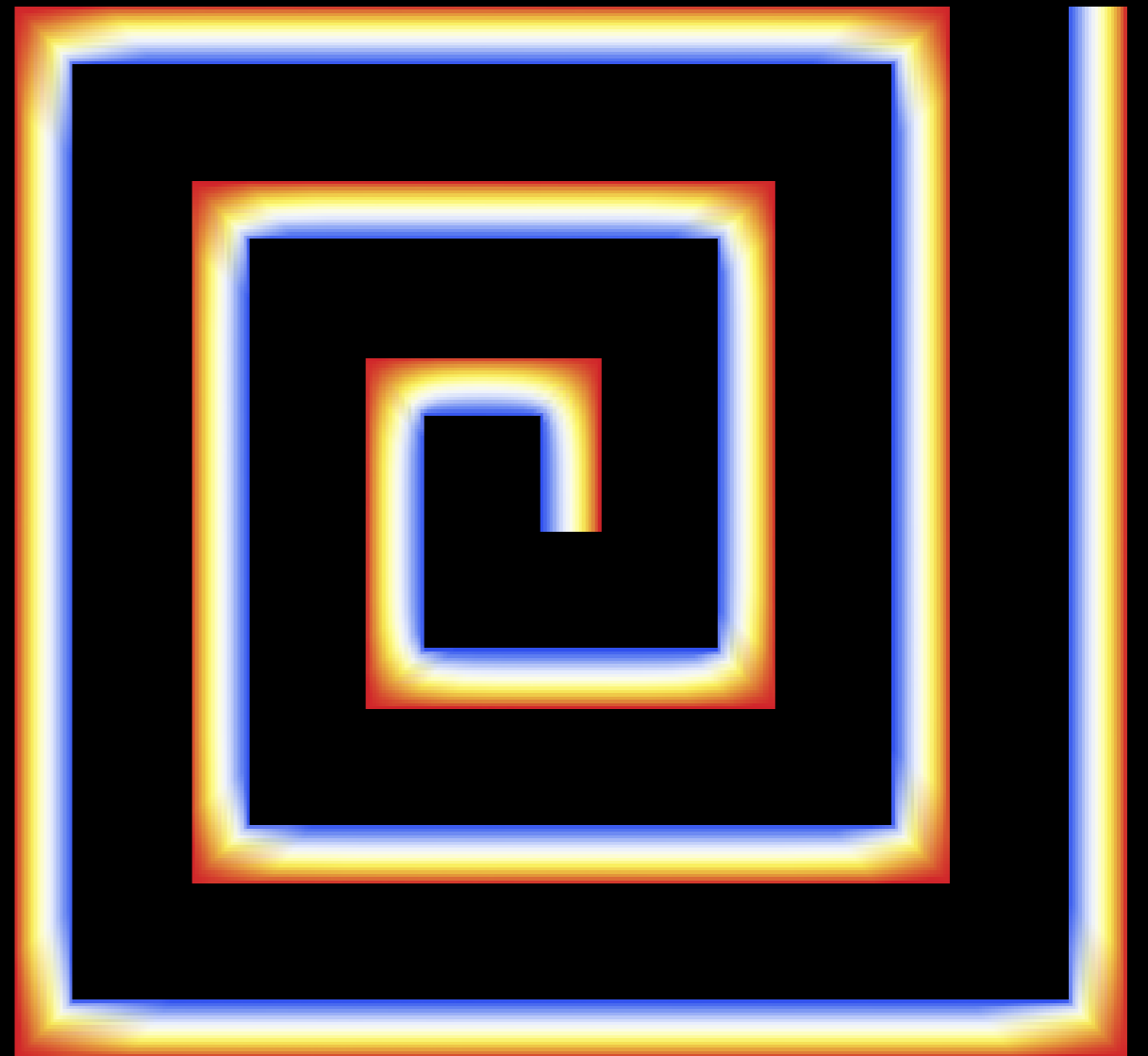
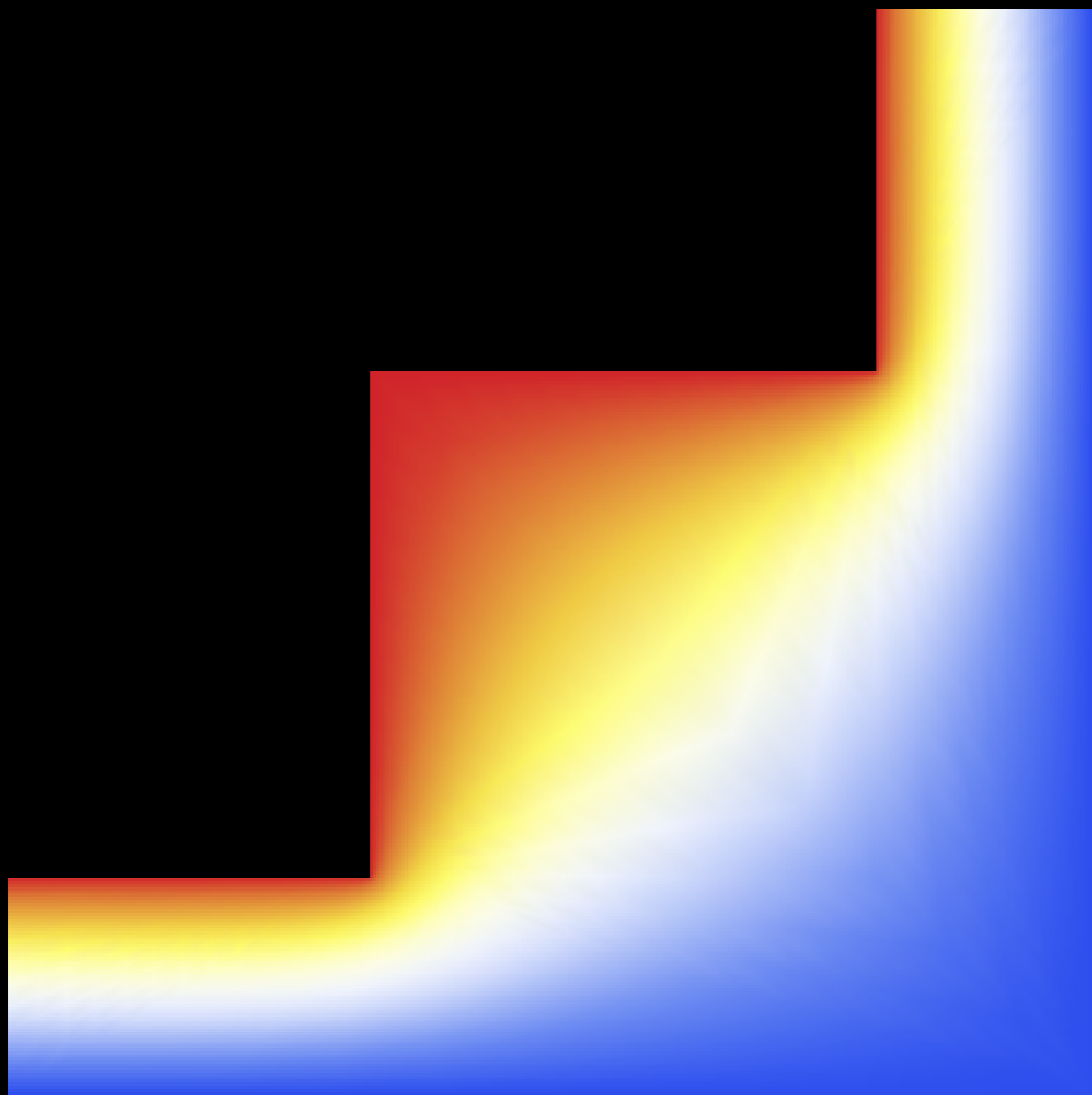
Conformal modulus: $M(R) = 2\pi / \text{cap } R$

Domains of Interest

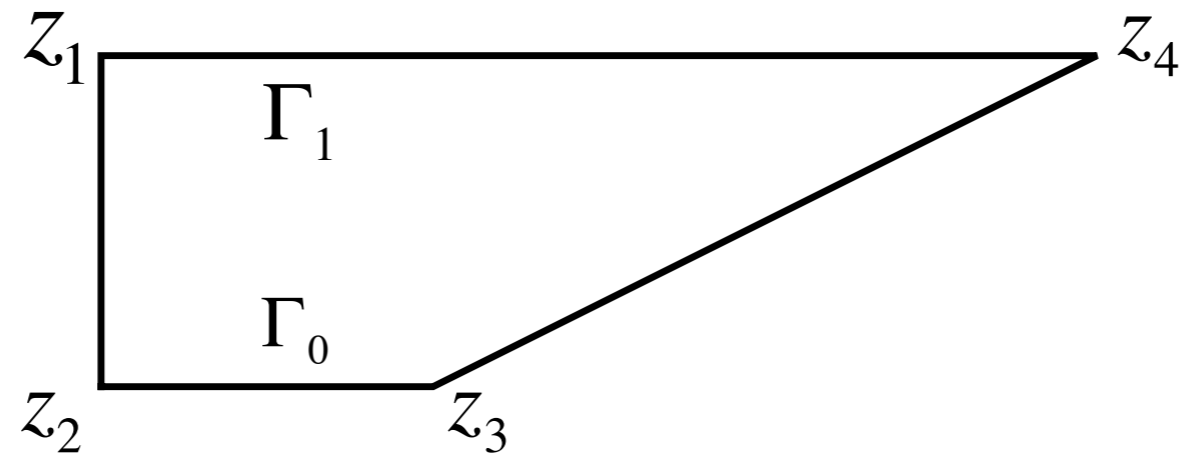








Model Problem



$$\Delta u = 0, \quad \text{in } \Omega,$$

$$u = 0, \quad \text{on } \Gamma_0,$$

$$u = 1, \quad \text{on } \Gamma_1,$$

$$\frac{\partial u}{\partial n} = 0, \quad \text{on } \Gamma_2 \cup \Gamma_3,$$

Variational problem: Find $u \in V$ such that

$$a(u, v) = 0, \quad \forall v \in V,$$

where

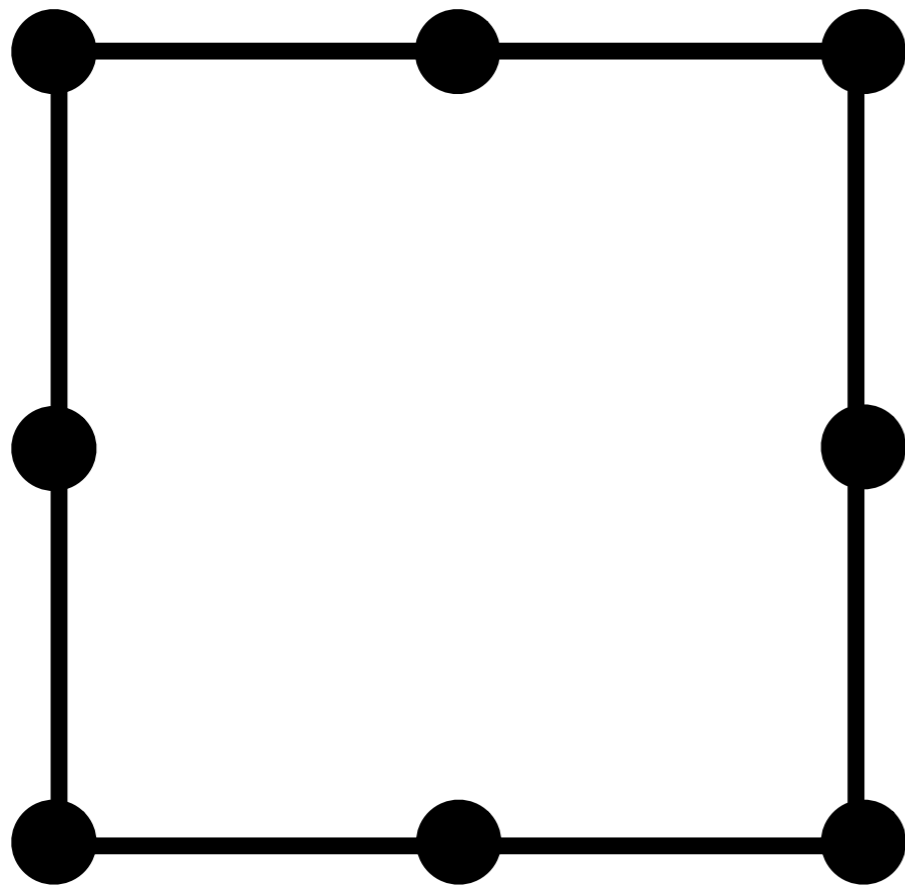
$$a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v \, d\omega,$$

$$V = H_0^1.$$

FEM in 20s

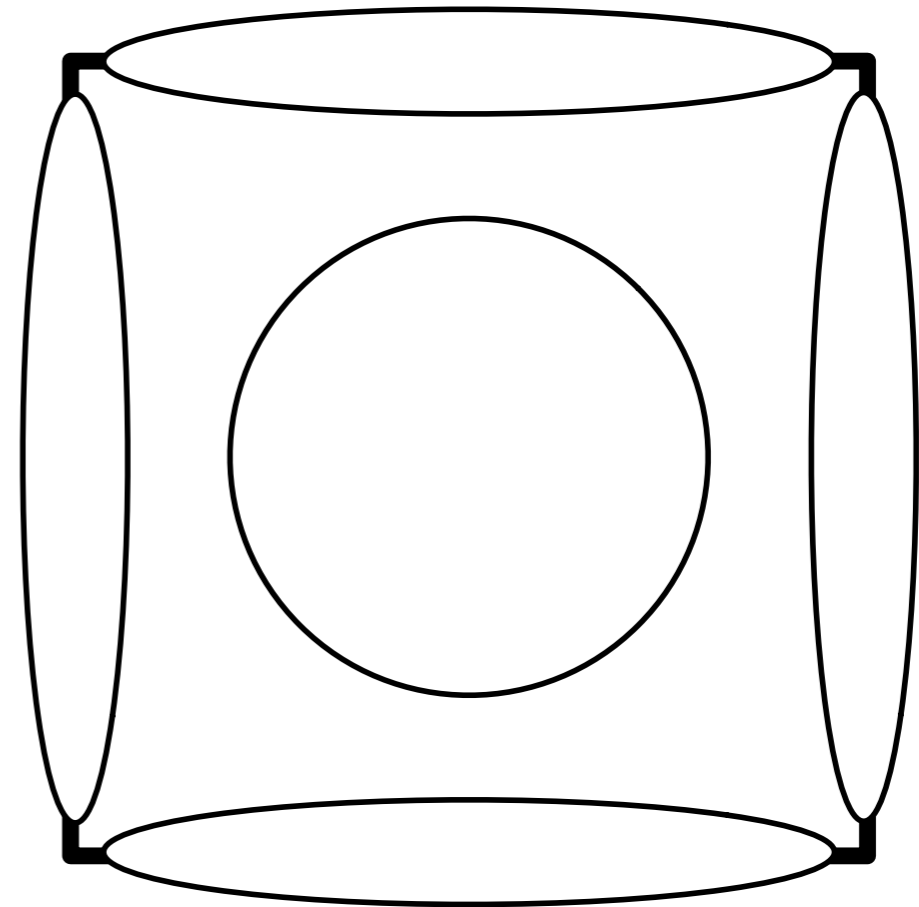
- Choose your finite elements
- Discretize the computational domain
- Compute the local contributions of different elements
- Sum the local contributions to form a global system; set up the right hand side from the boundary conditions
- Solve the global linear system
- Solution minimizes the energy!

h- vs p-FEM Elements



Nodal degrees of freedom

Lagrange



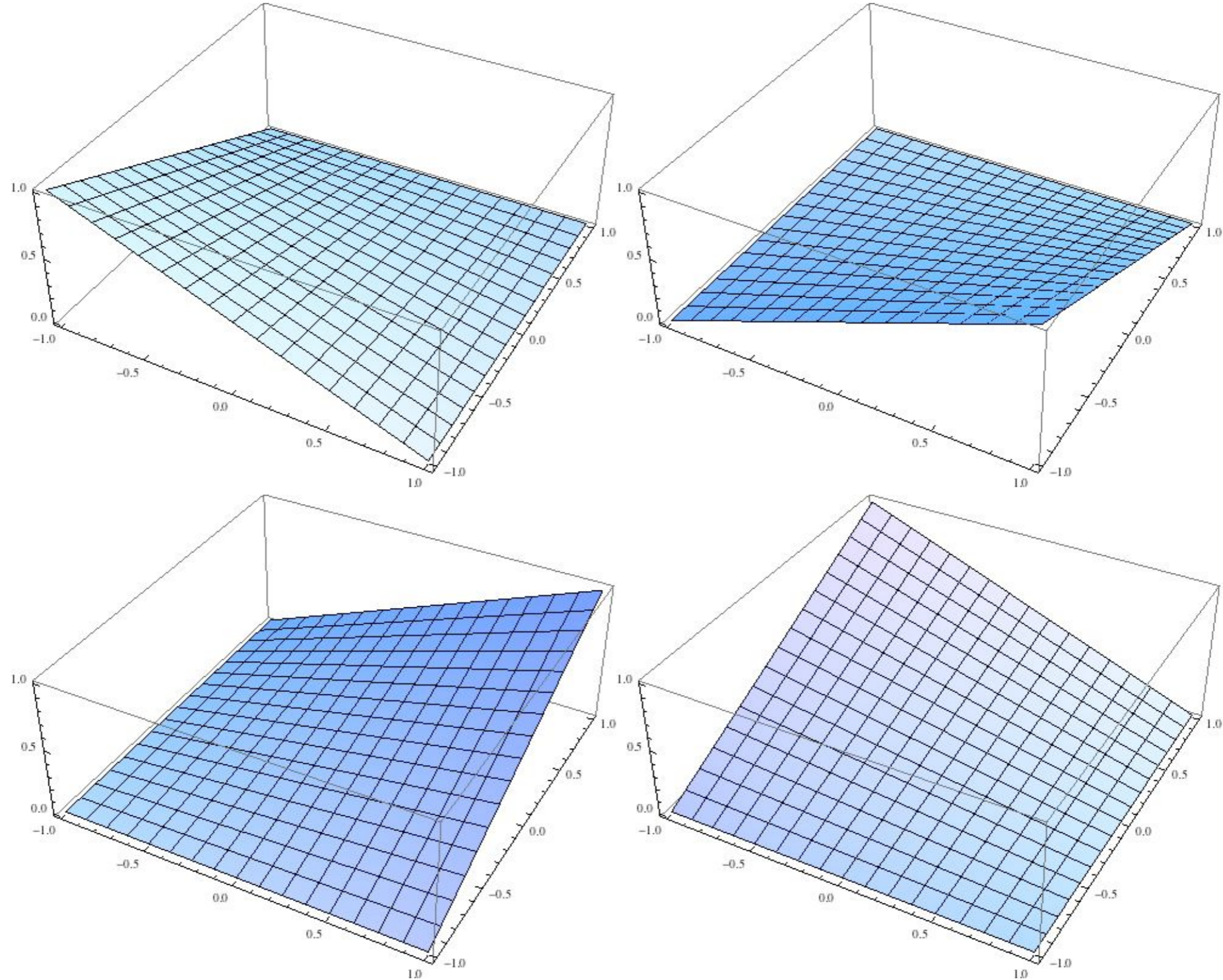
Modal degrees of freedom

Legendre

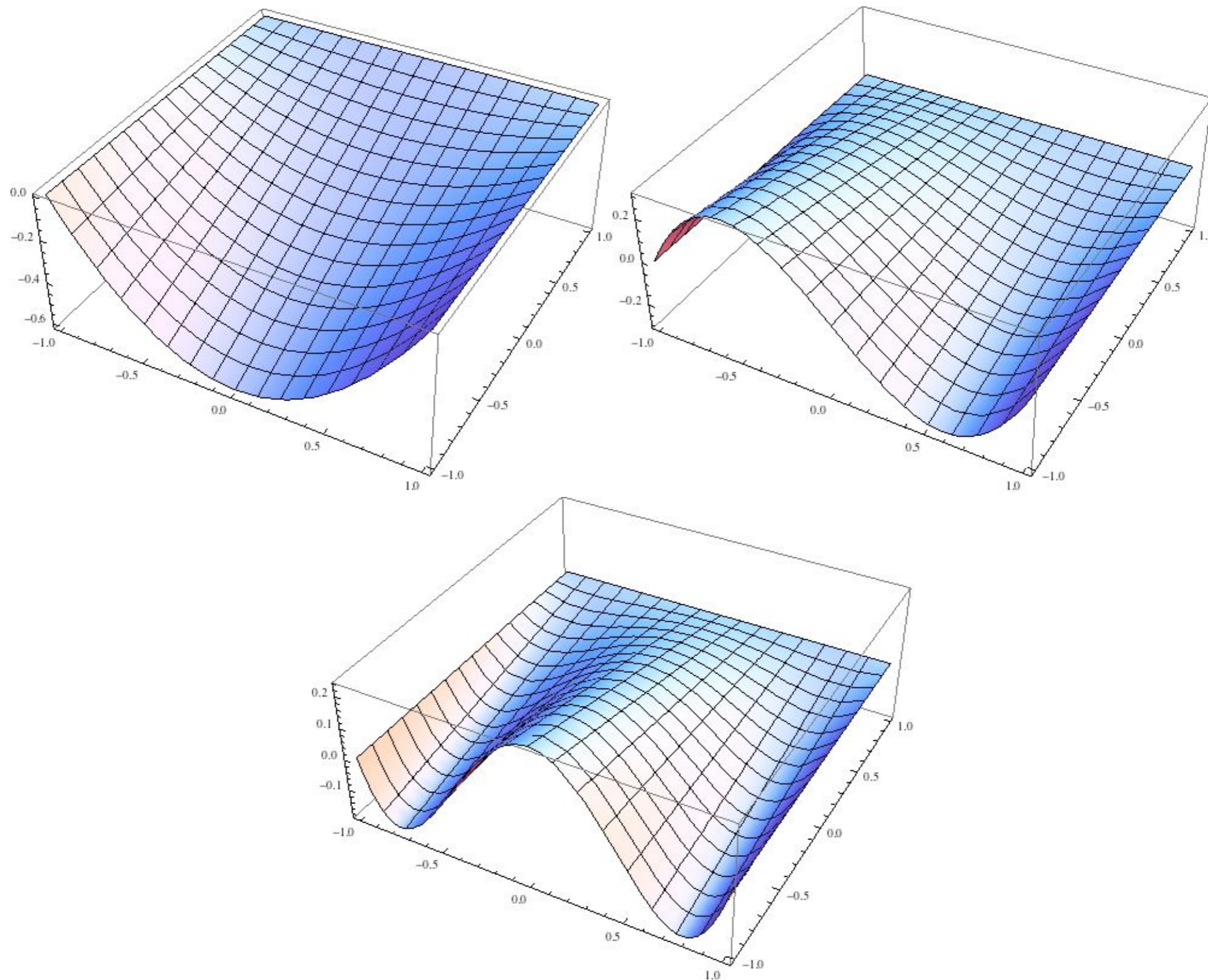
hp-Method

- h-method or classical FEM
 - Refine the mesh
- p-method
 - Keep the mesh fixed, increase the order of basis polynomials
- hp-method: Combine h and p!
- Number of unknowns $\sim \# \text{elements } p^2$

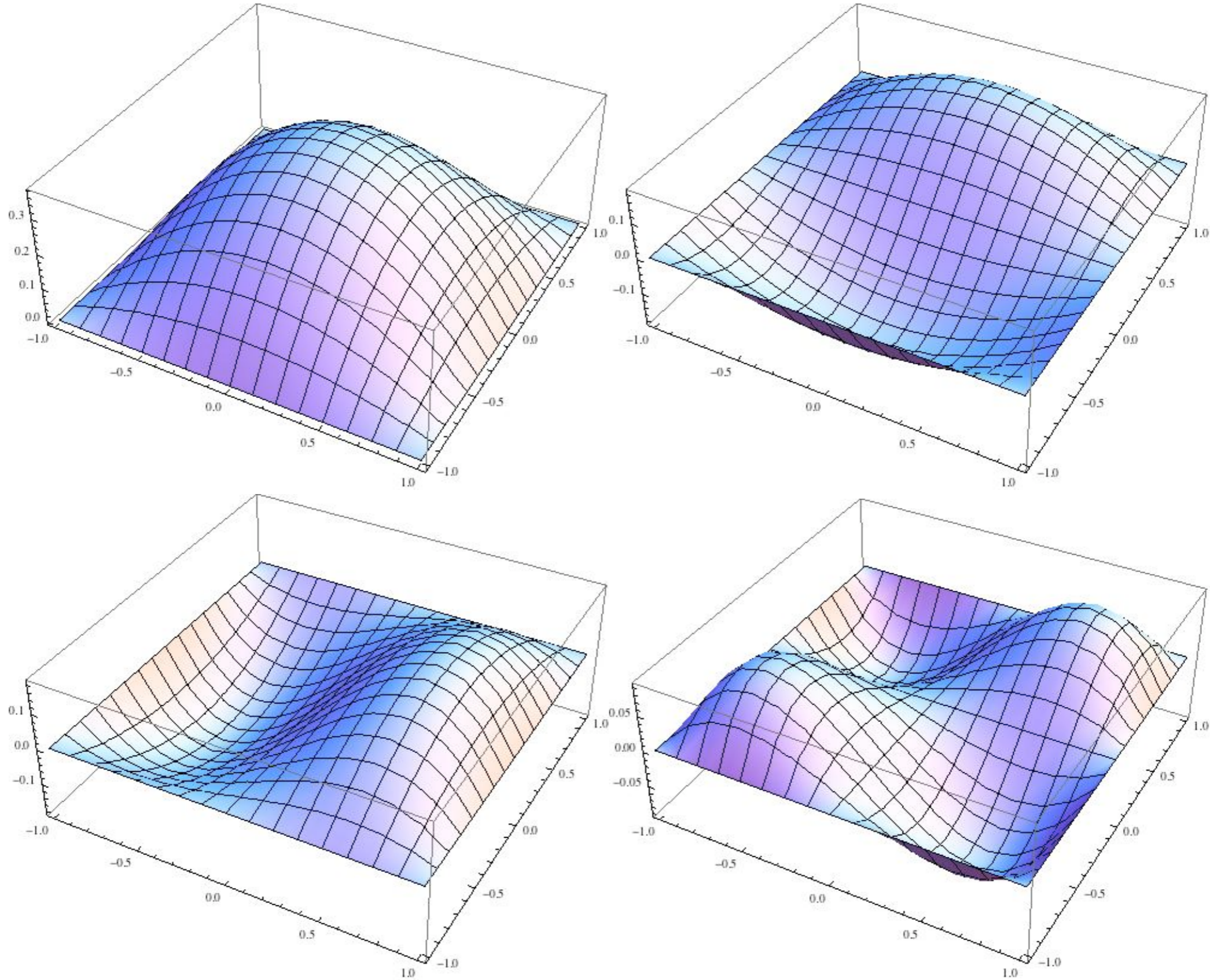
Linear Modes



Side Modes



Inner Modes



Exponential Convergence

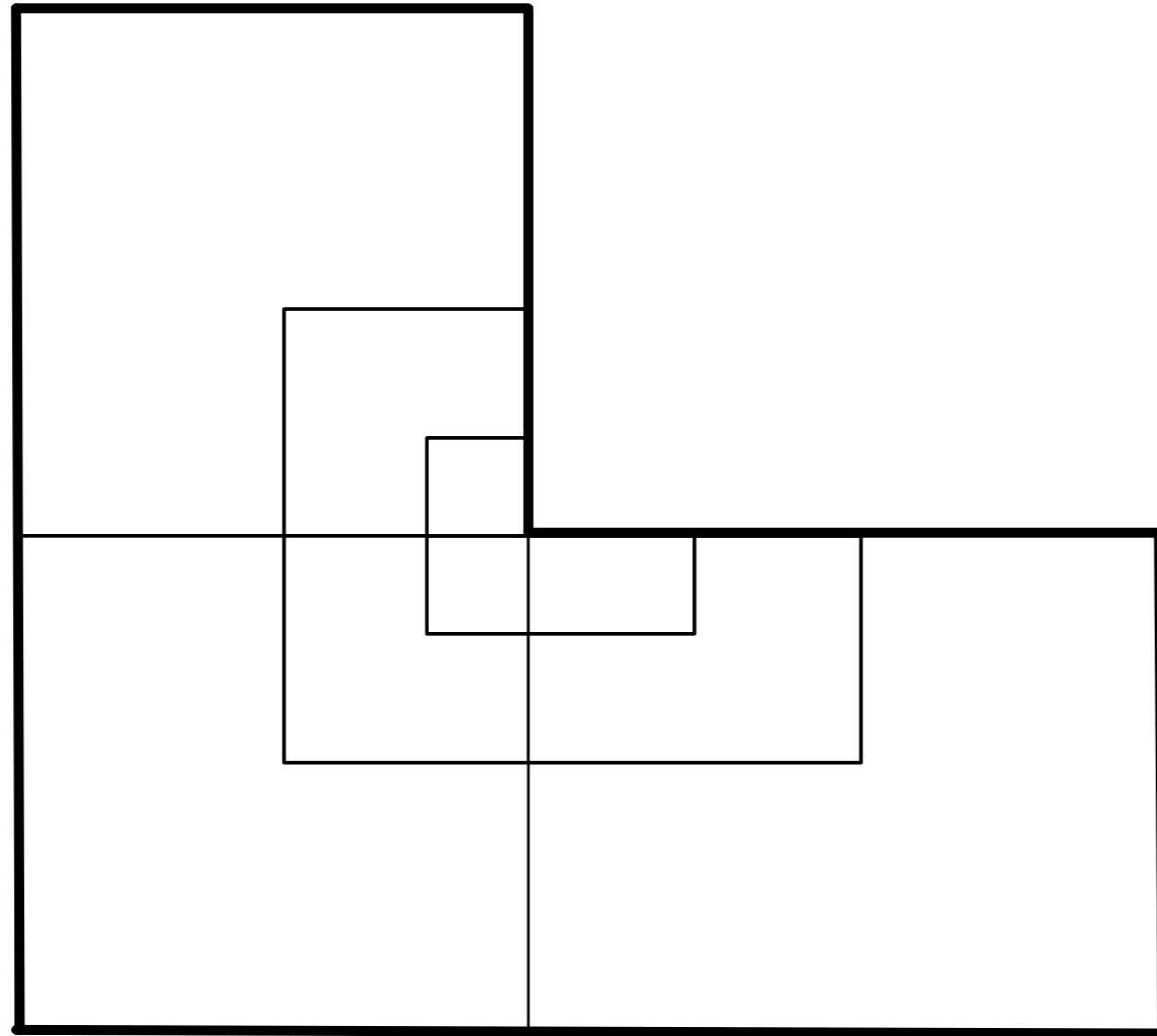
Theorem [Babuska & Guo]

Let $\Omega \subset \mathbb{R}^2$ be a polygon, v the FEM-solution, and the weak solution u_0 sufficiently smooth. Then

$$\inf_v \|u_0 - v\|_{H^1(\Omega)} \leq C \exp(-b\sqrt[3]{N}),$$

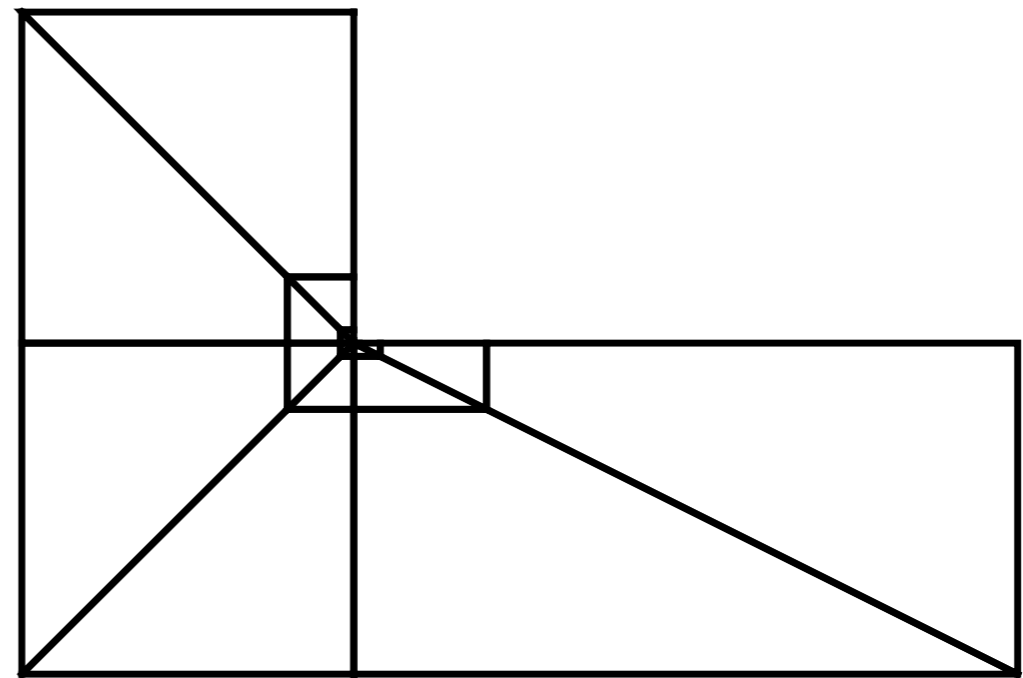
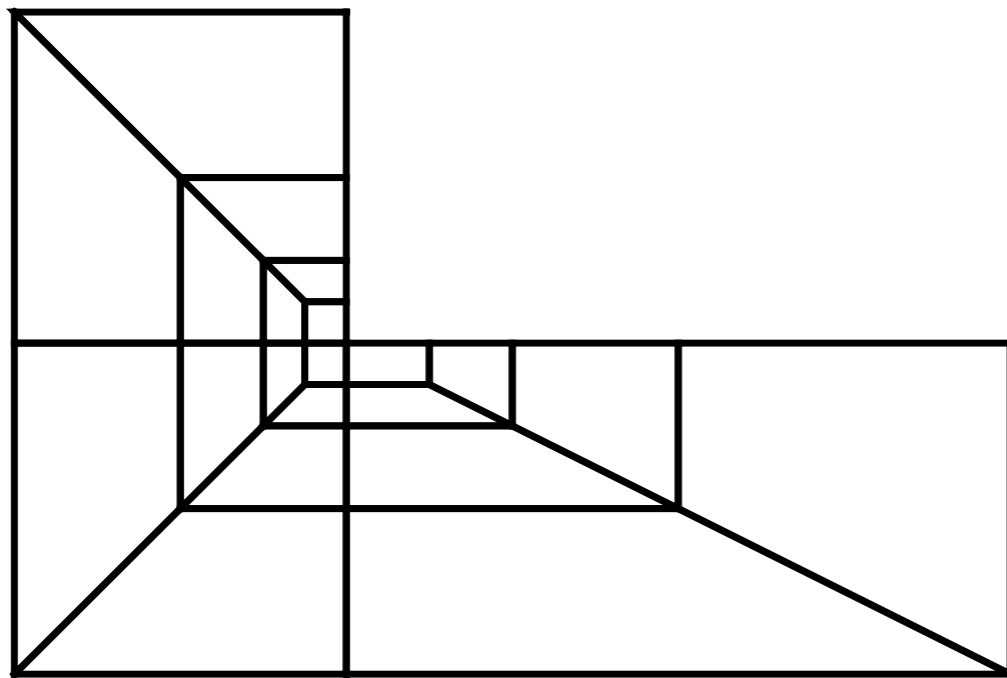
where C and b are independent of N , the number of degrees of freedom. Here v is computed on a proper geometric mesh, where the orders of individual elements depend on their originating layer, such that highest layers have smallest orders.

Geometric Mesh



Scaling and Nesting

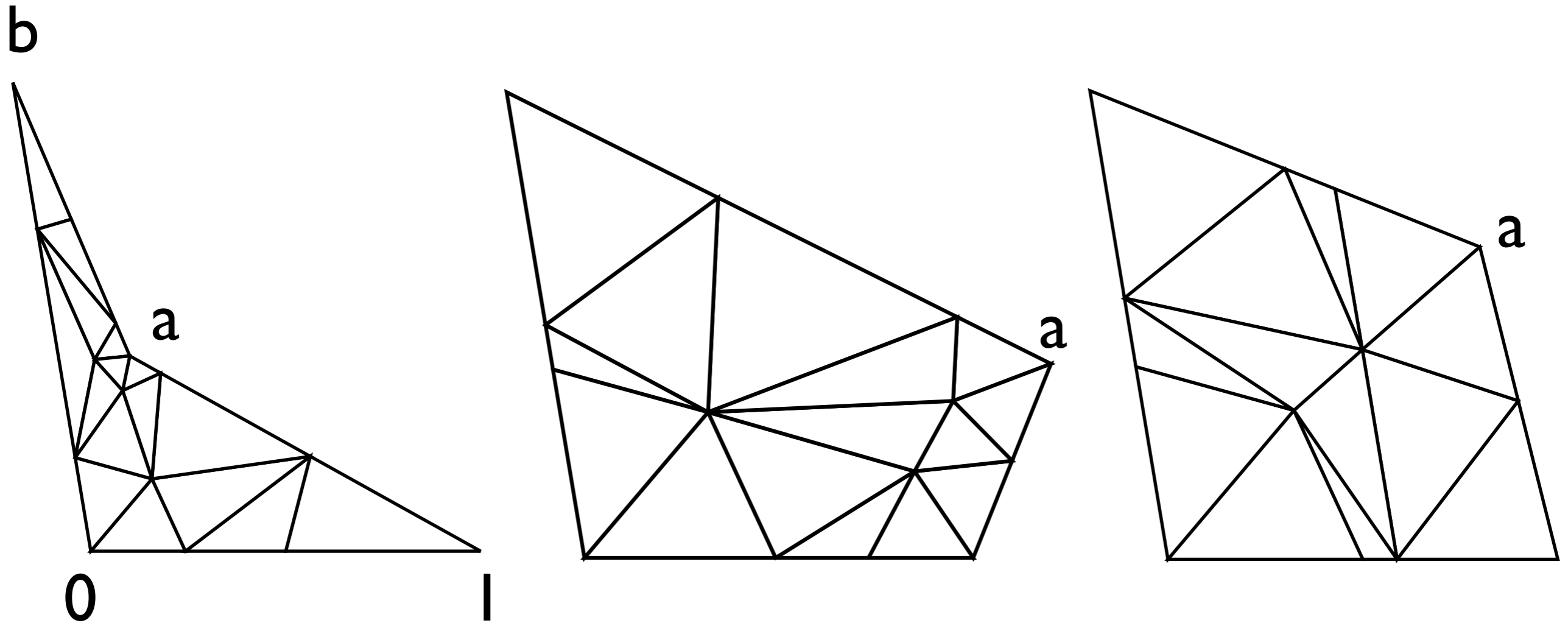
(α, ν) -meshes



α	Scaling Factor	0.5	0.2
ν	Nesting Level	3	3

Case Study: Family of Quadrilaterals

Sample Meshes



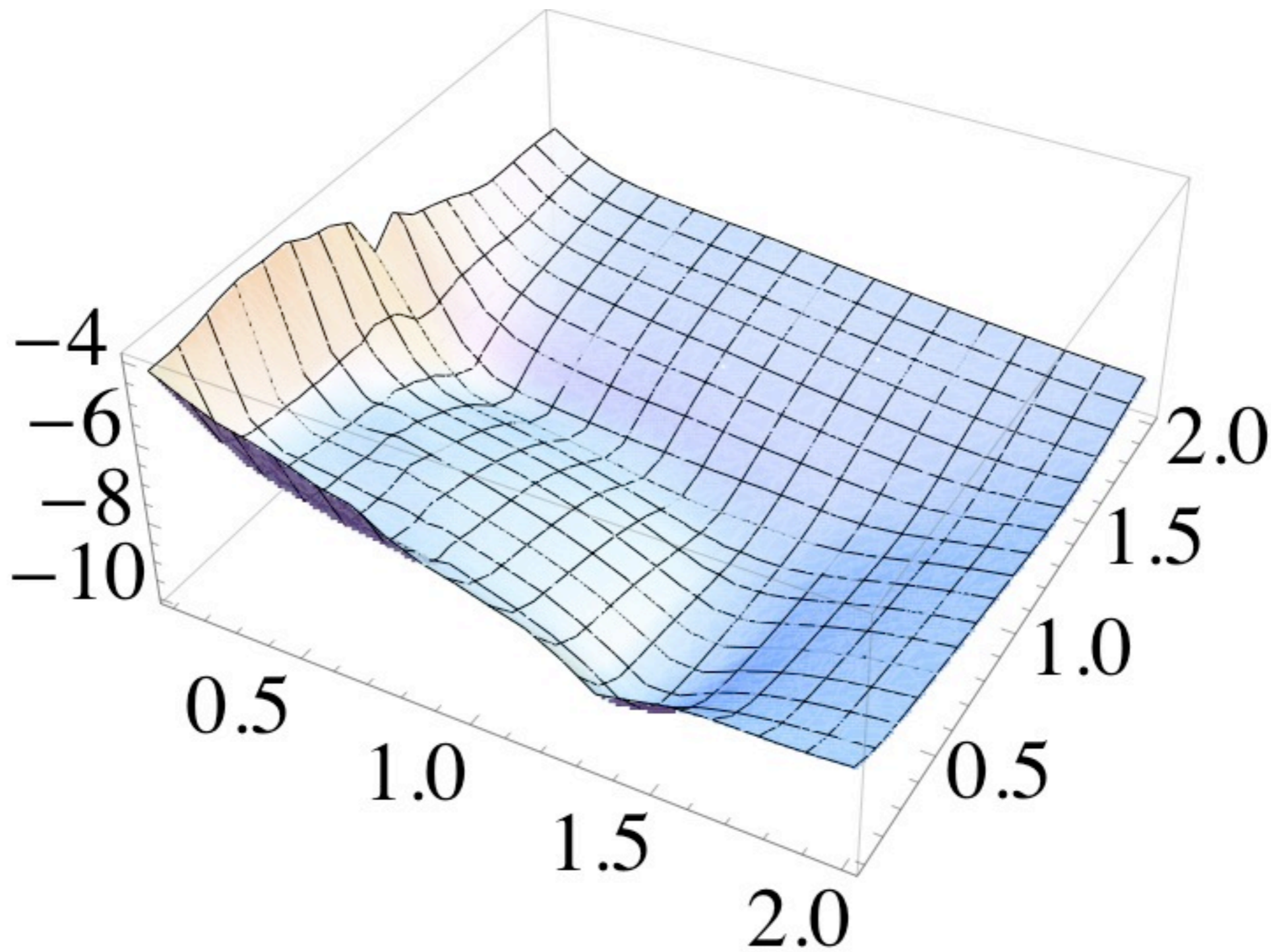
Three corners are fixed: $\{0, 1, -0.2 + 1.2i\}$

Let the fourth corner get values inside $[0.1, 2] \times [0.1, 2]$.

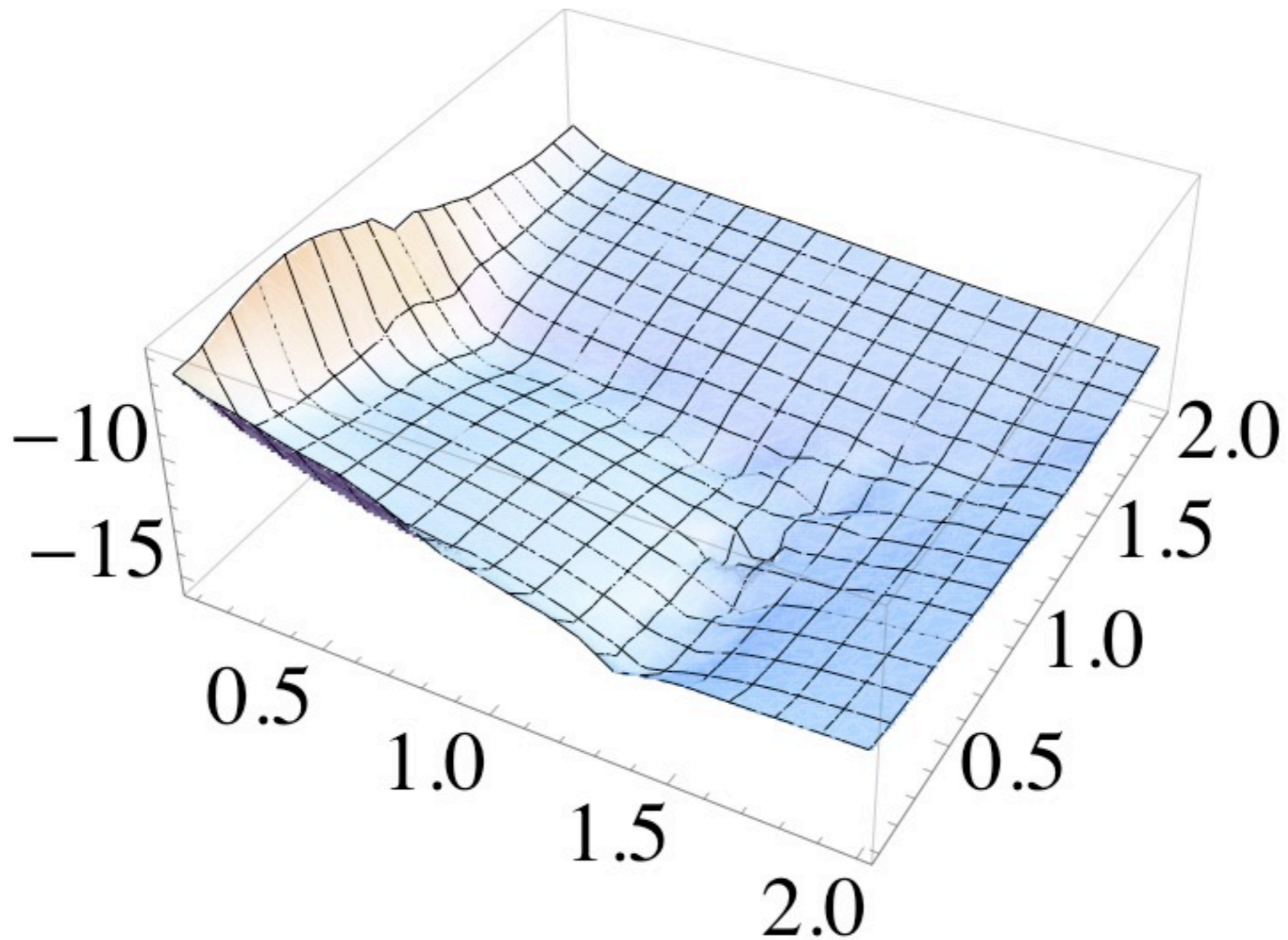
Numerical Experiments

- Given $0, l, b$, choose the fourth corner; a
- Compute the domains corresponding to $M(D; a, b, 0, 1) \cdot M(D; (b-1)/(a-1), 1/(1-a), 0, 1) = 1$
- Create the (α, ν) -meshes: $(0.15, 12)$
- Solve the systems for $p=1, \dots, 20$
- Compute the reciprocal identity – 1
- $\text{Log} | 0$ indicates the number of correct decimals

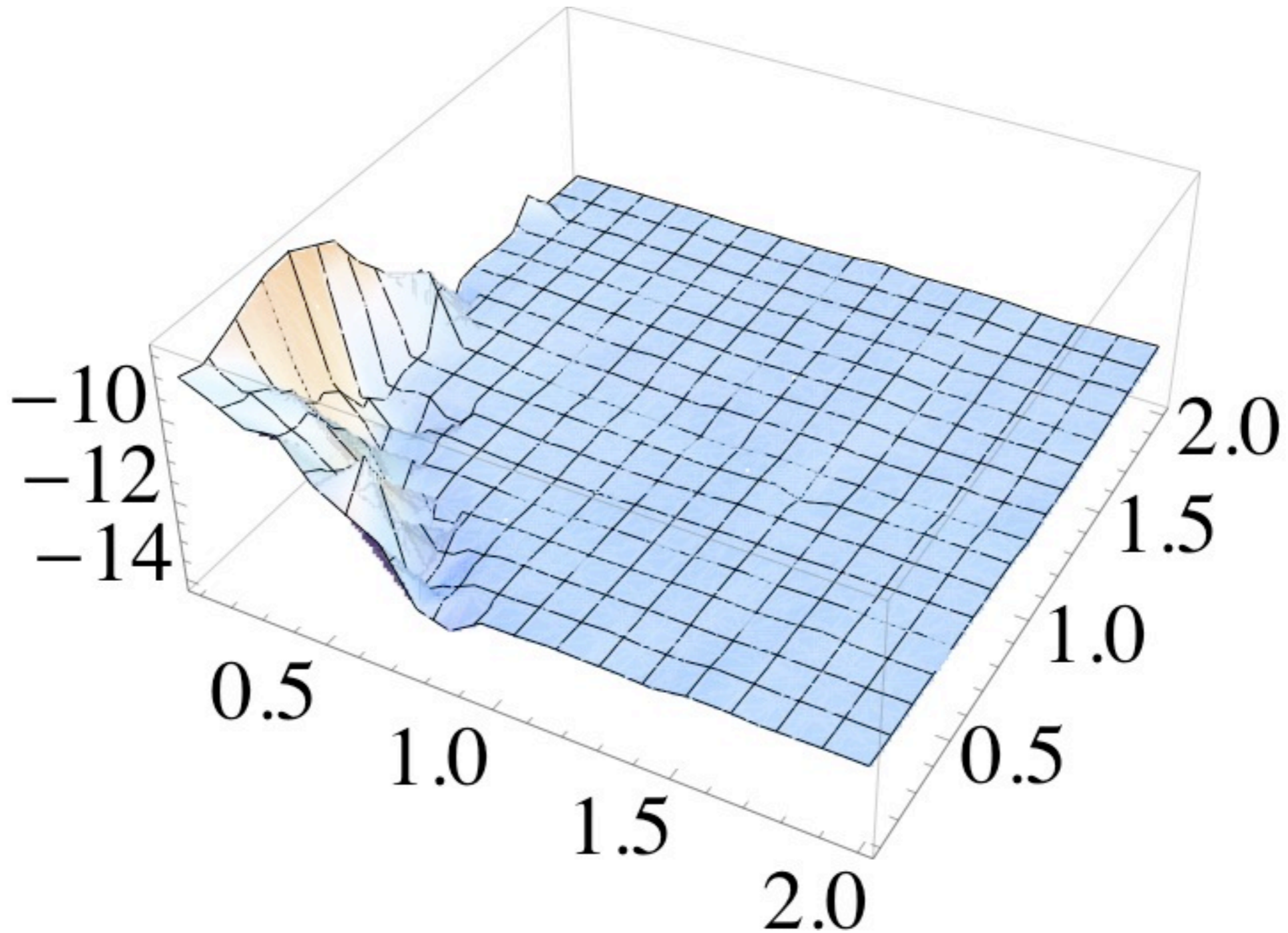
$p=8$, Log10 Error



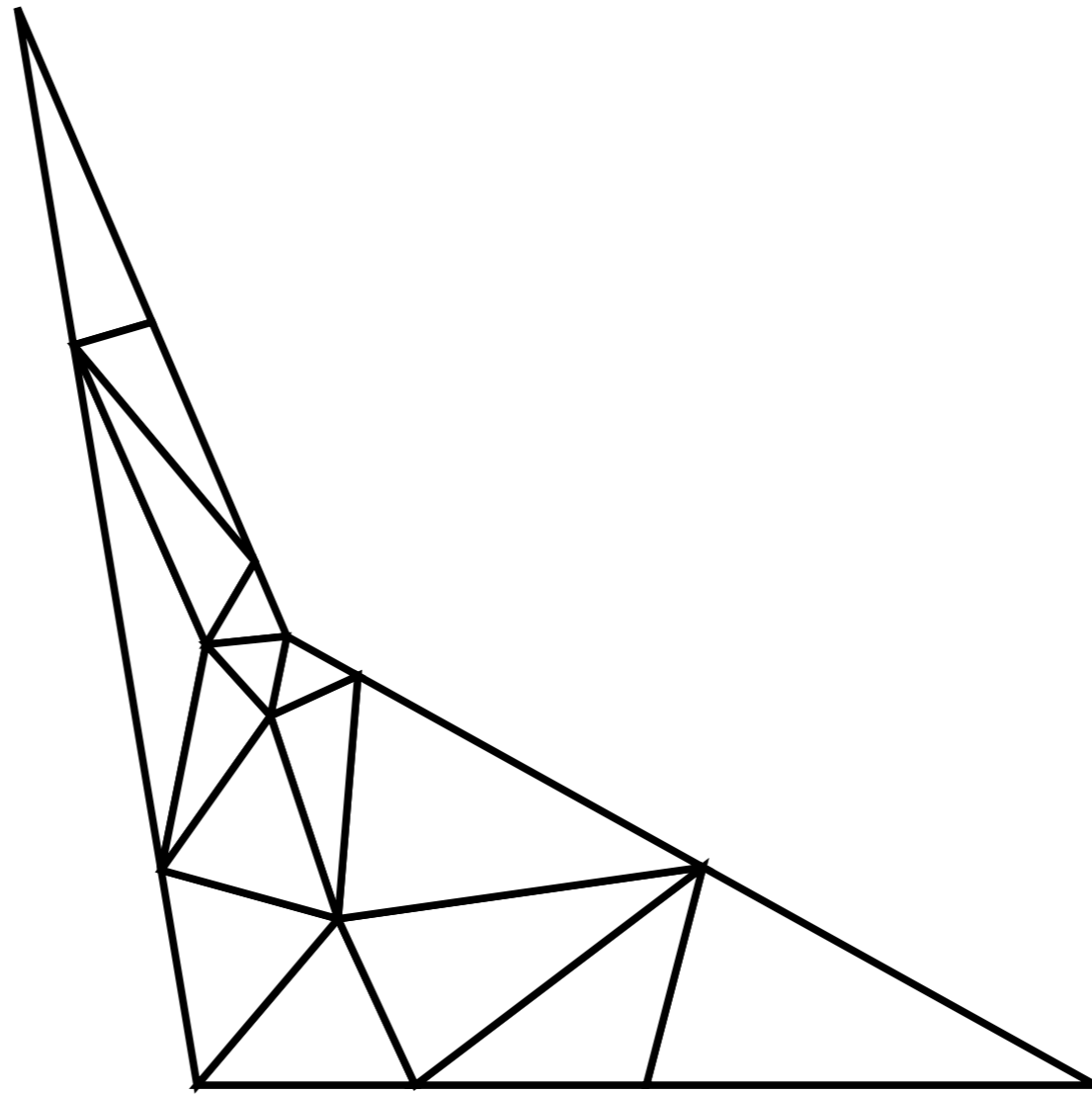
$p=13$, Log10 Error



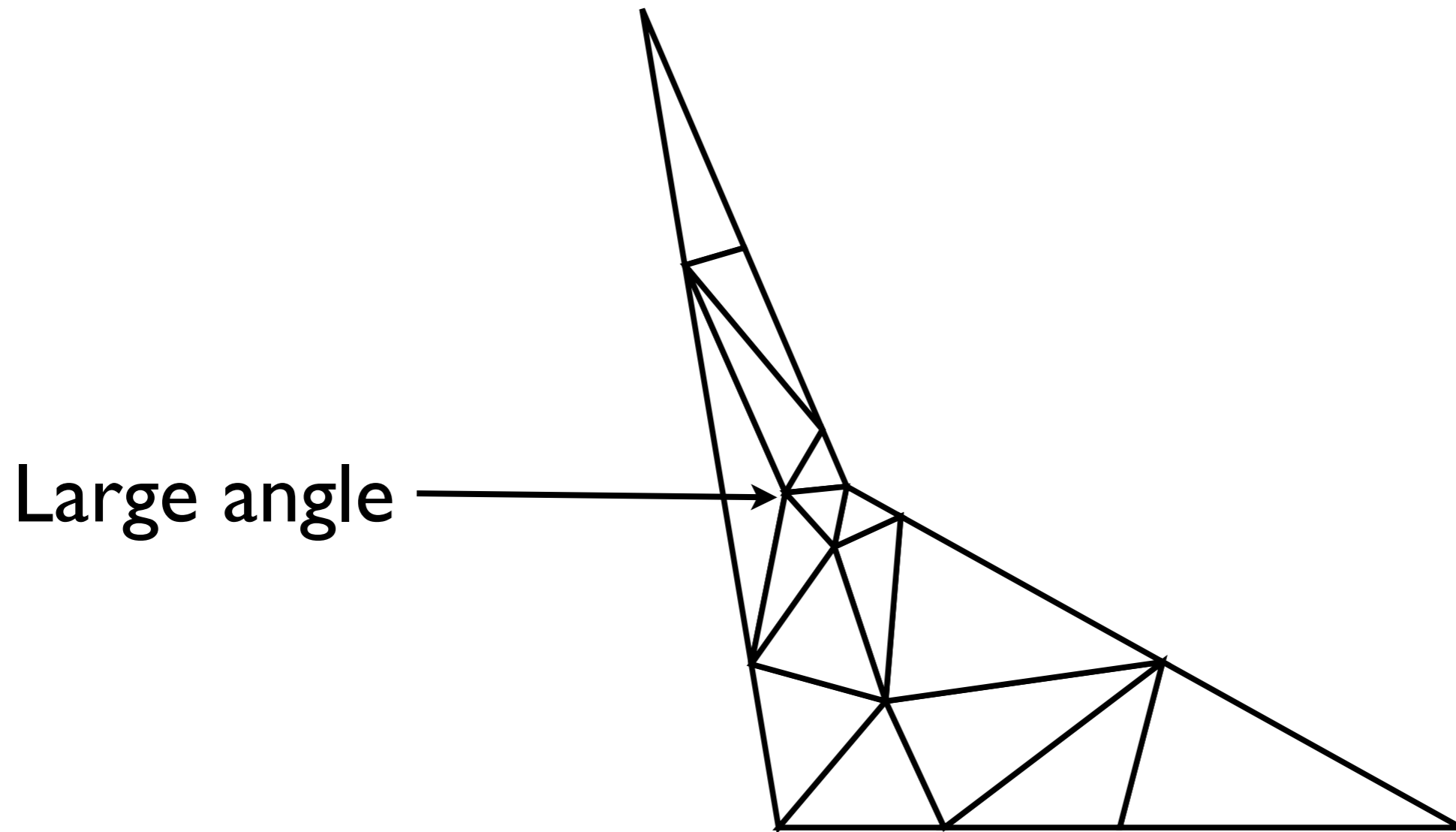
$p=20$, Log10 Error



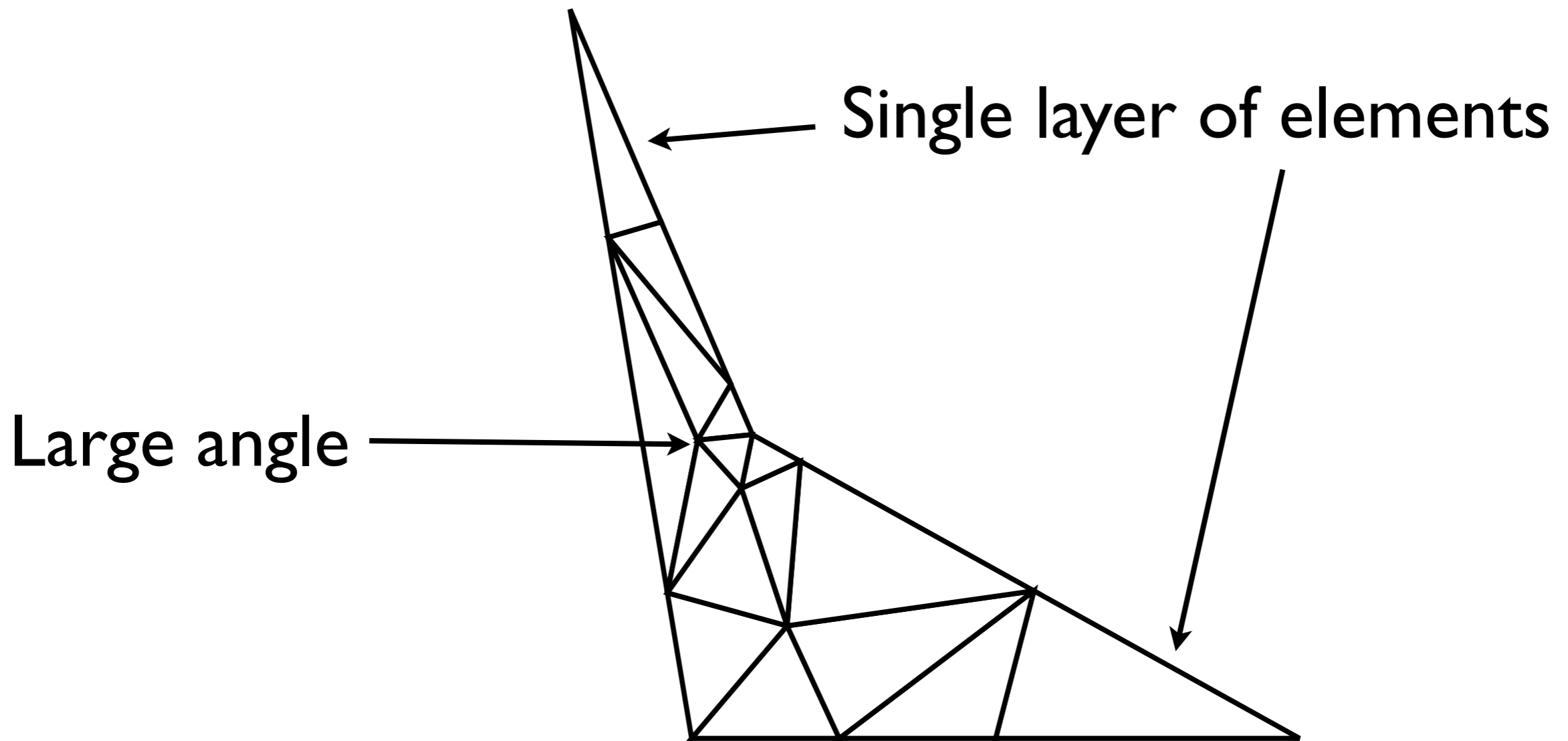
Maximal Error Case



Maximal Error Case



Maximal Error Case



Comments

- For certain geometries computation of moduli is akin to evaluation of special functions.
- Code will be available if you ask kindly. Documentation is somewhat lacking.
- Implemented in Mathematica.

Challenges

- What is the best possible initial mesh?
 - Large angles vs small angles
- Is a posteriori error analysis feasible?
- What about moduli in higher dimensions?
 - p -Laplace, non-linear

Reference

Helsinki University of Technology Institute of
Mathematics Research Reports A575

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